

On the Meet-in-the-Middle Attack

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General

New Algorithm

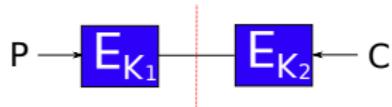
Conclusion

Meet-in-the-middle attack

- ▶ Introduced by Diffie-Hellman
- ▶ Recover the 2 keys of 2DES by finding a collision in the middle of the cipher

$$E_{K_2} \circ E_{K_1}(P) = C$$

Meet-in-the-middle attack

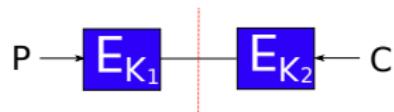


Problem: $E_{K_1}(P) = E_{K_2}^{-1}(C)$

Given two pairs $(P_1, C_1), (P_2, C_2)$:

- ▶ For all keys K_1 save in a hash table H the values $(E_{K_1}(P_1), E_{K_1}(P_2), K_1)$
- ▶ For each key K_2 check if $(E_{K_2}^{-1}(C_1), E_{K_2}^{-1}(C_2))$ is in H
- ▶ Match corresponds to the secret key $K_1||K_2$

Meet-in-the-middle attack



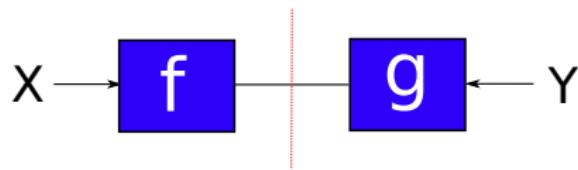
Problem: $E_{K_1}(P) = E_{K_2}^{-1}(C)$

To recover the $2n$ -bit key $K_1||K_2$:

- ▶ Time: 2^n to create H and 2^n to find a match
- ▶ Memory: 2^n to save H

MITM = Collision

- ▶ Today, MITM attack is synonym for collision search between two functions.
- ▶ Example, MITM attacks on AES have nothing to do with "meeting in the middle".
- ▶ So, instead of MITM we can talk about collisions.



Collisions: Types

Usually, there are two types of collisions between f and g

1. f, g **have range larger than domain.**

Recover the unique 2 keys of 2DES given 2 pairs (P, C) .

2. **Range not larger than domain.**

Find some 2 keys of 2DES given 1 pair (P, C) .

Our target: Unbalanced Collisions

Deal only with the case 2.

To simplify, focus only on collision search between two functions f, g :

$$f : \{0, 1\}^n \rightarrow \{0, 1\}^n$$

$$g : \{0, 1\}^n \rightarrow \{0, 1\}^n$$

Unbalanced Collisions – g is R times more "expensive" than f

State-of-the-art

When $R = 1$ (f, g have the same cost) then

- ▶ use Floyd's cycle finding algorithm
- ▶ it requires time $T = 2^{\frac{n}{2}}$
- ▶ it requires **negligible** memory

State-of-the-art

When $R = 2^{\frac{n}{100}}$, then

- ▶ use DH MITM
- ▶ Store $2^{\frac{n}{2} - \frac{n}{200}}$ images of g
(in time $2^{\frac{n}{2} - \frac{n}{200}} \times 2^{\frac{n}{100}} = 2^{\frac{n}{2} + \frac{n}{200}}$)
- ▶ Produce around $2^{\frac{n}{2} + \frac{n}{200}}$ images of f and check for collision
- ▶ Success because $2^{\frac{n}{2} - \frac{n}{200}} \times 2^{\frac{n}{2} + \frac{n}{200}} = 2^n$

Time: $2^{\frac{n}{2} + \frac{n}{200}}$

Memory: $2^{\frac{n}{2} - \frac{n}{200}}$

State-of-the-art

Table: Complexities

R	Time	Memory
1	$2^{\frac{n}{2}}$	negl
$2^{\frac{n}{100}}$	$2^{\frac{n}{2} + \frac{n}{200}}$	$2^{\frac{n}{2} - \frac{n}{200}}$

Tradeoff

In general, when $R > 1$,

$$T = 2^{\frac{n}{2}} \cdot \sqrt{R}$$

$$M = 2^{\frac{n}{2}} / \sqrt{R}$$

Tradeoff:

$$TM = 2^n$$

where $T \geq \sqrt{R} \cdot 2^{\frac{n}{2}}$.

Observation

- ▶ When $R = 1$ we use Floyd's algorithm \implies negl. memory
- ▶ When $R > 1$ we use standard MITM \implies huge memory

Find the missing link (algorithm):

The smaller R , the smaller memory requirement

General

New Algorithm

Conclusion

Ideas

New algorithm combines 2 ideas:

1. Unbalanced interleaving
2. van Oorschot-Wiener parallel collision search

Unbalanced interleaving

Balanced interleaving

Floyd's algorithm used for collision search of 2 balanced functions selects the used function with equal probability. I.e. it finds a collision for $F(x)$ defined as

$$F(x) = \begin{cases} f(x) & \text{if } \sigma(x) = 0 \\ g(x) & \text{if } \sigma(x) = 1 \end{cases}$$

$\sigma(x)$ outputs 0 or 1, with equal probability

Collisions for $F(x)$ is collision between f, g with probability $\frac{1}{2}$
⇒ repeat the search 2 times

Unbalanced interleaving

Unbalanced interleaving

Define $F(x)$ as

$$F(x) = \begin{cases} f(x) & \text{if } \sigma(x) = 0 \\ g(x) & \text{if } \sigma(x) = 1 \end{cases}$$

$\sigma(x)$ outputs 0 around R times more often than 1

Collisions for $F(x)$ is collision between f, g with probability $\frac{1}{R}$
⇒ repeat the search R times

Multiple collisions for $f(x)$

- ▶ Floyd's algorithm with time $2^{\frac{n}{2}}$ is optimal to find one collision
- ▶ However, sometimes we need multiple collisions
- ▶ If s collisions are required, then Floyd needs $s \cdot 2^{\frac{n}{2}}$ time
- ▶ It needs negligible memory

van Oorschot-Wiener Parallel Collision Search

van Oorschot-Wiener algorithm can be used to find multiple collisions faster:

- ▶ Useful when s is larger
- ▶ It requires memory

van Oorschot-Wiener Algorithm: Hash Table

First, construct a hash table:

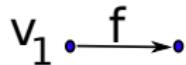
- ▶ Take a random point v_1 and produce a chain of values
 $v_i = f(v_{i-1}), i = 2, \dots, 2^{\frac{n-m}{2}}$
- ▶ Store $(v_{2^{\frac{n-m}{2}}}, v_1)$ in hash table H
- ▶ Repeat for 2^m different points

$v_1 \bullet$

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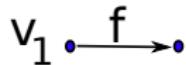
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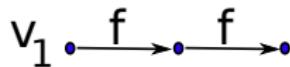
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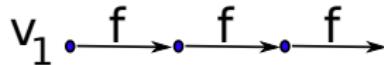
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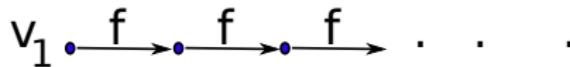
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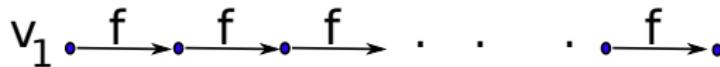
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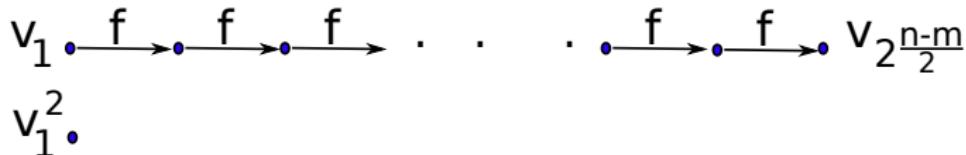
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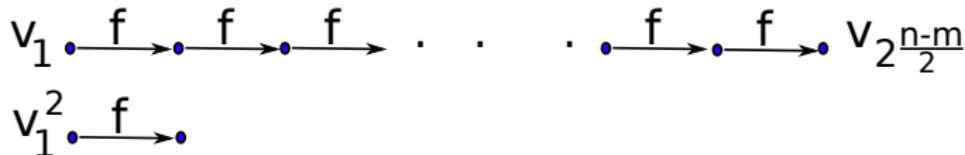
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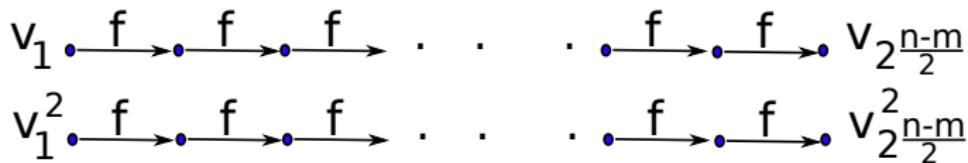
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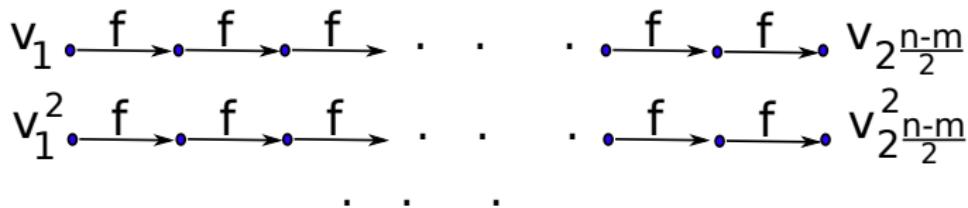
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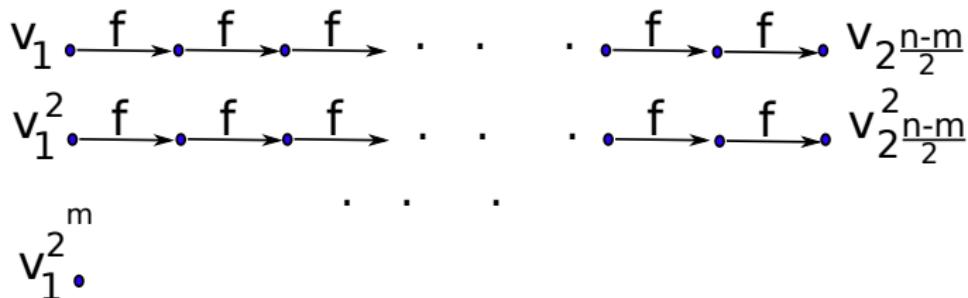
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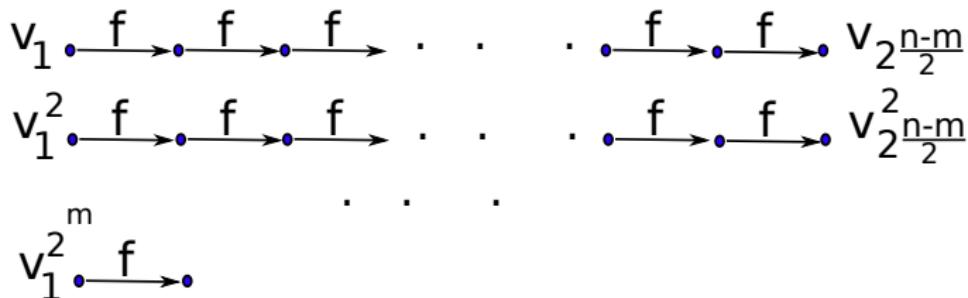
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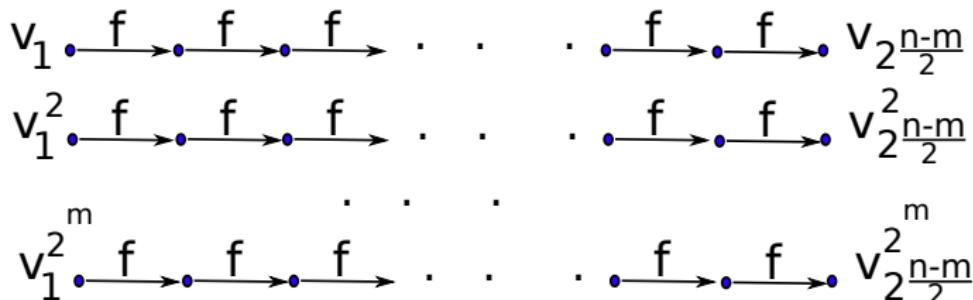
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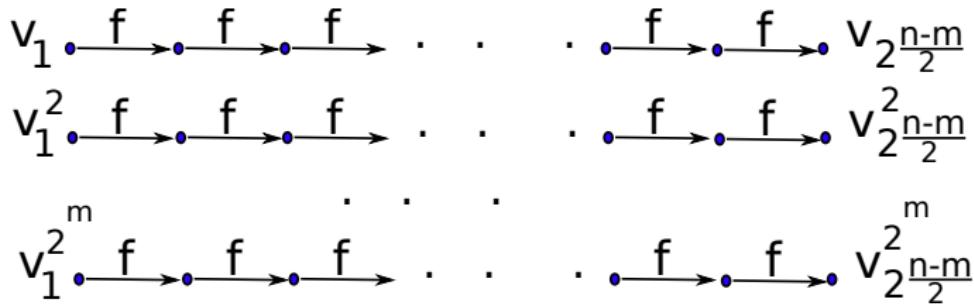
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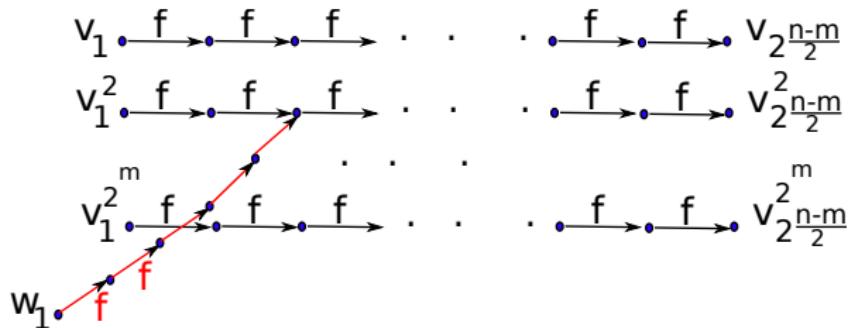
Construction of H :

- ▶ Time: $2^m \times 2^{\frac{n-m}{2}} = 2^{\frac{n+m}{2}}$ calls to $f(x)$
- ▶ Memory: 2^m



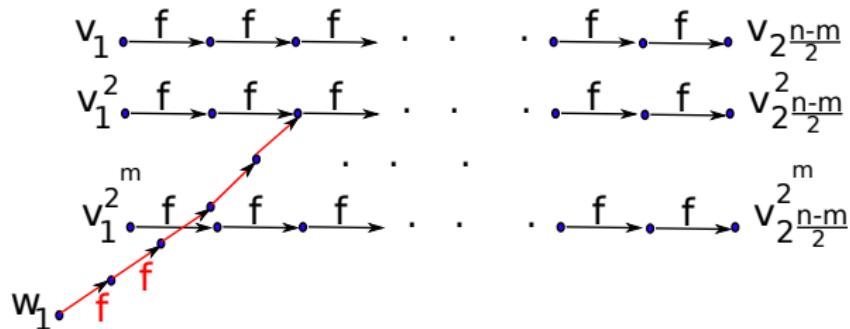
van Oorschot-Wiener Algorithm: Collision Search

1. Pick a random value w_1
2. Produce $w_i = f(w_{i-1})$
3. Check if w_i is in H . If not go to 2
4. By backtracking find the colliding values



van Oorschot-Wiener Algorithm: Collision Search

- ▶ During construction of H passed $2^{\frac{n+m}{2}}$ values
- ▶ If chain of w_i 's is of length around $2^n/2^{\frac{n+m}{2}} = 2^{\frac{n-m}{2}}$ a collision will occur
- ▶ Time complexity of one collision: $2^{\frac{n-m}{2}}$



van Oorschot-Wiener Algorithm: Summary

- ▶ Initial cost for H : time $2^{\frac{n+m}{2}}$, memory 2^m
- ▶ Subsequent s collisions cost: $s \cdot 2^{\frac{n-m}{2}}$

When $2^{\frac{n+m}{2}} + s \cdot 2^{\frac{n-m}{2}} < s \cdot 2^{\frac{n}{2}}$
then van Oorschot-Wiener outperforms Floyd

Example: $s = 2^{\frac{n}{3}}$ collisions and $2^{\frac{n}{3}}$ memory

- ▶ van Oorschot-Wiener : $2^{\frac{2n}{3}}$
- ▶ Floyd: $2^{\frac{5n}{6}}$

New Algorithm for Unbalanced Collision Search

1. Define $F(x)$ as

$$F(x) = \begin{cases} f(x) & \text{if } \sigma(x) = 0 \\ g(x) & \text{if } \sigma(x) = 1 \end{cases}$$

$\sigma(x)$ outputs 0 around R times more often than 1

2. Construct hash table H for $F(x)$ with $M = 2^m$ entries
3. Find collision for $F(x)$. If not a collision for f, g repeat step 3

After repeating 3. around R times, collision for f, g will appear

New Algorithm: Complexity

1. Define $F(x)$ as

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2. Construct hash table H for $F(x)$ with $M = 2^m$ entries
3. Find collision for $F(x)$. If not a collision for f, g repeat step 3 (repeated R times)

Memory: $M = 2^m$

Time:

- ▶ Step 2:

Calls to $F(x)$: $2^{\frac{n+m}{2}}$

Calls to f : $2^{\frac{n+m}{2}}$

Calls to g : $2^{\frac{n+m}{2}}/R$, but cost $2^{\frac{n+m}{2}}$

- ▶ Step 3:

Calls to $F(x)$: $R \cdot 2^{\frac{n-m}{2}}$

Calls to f : $R \cdot 2^{\frac{n-m}{2}}$

Calls to g : $2^{\frac{n-m}{2}}$, but cost $R \cdot 2^{\frac{n-m}{2}}$

Total: $T = 2^{\frac{n+m}{2}} + R \cdot 2^{\frac{n-m}{2}}$

New Algorithm: Complexity

$$M = 2^m$$

$$T = 2^{\frac{n+m}{2}} + R \cdot 2^{\frac{n-m}{2}}$$

When $2^{\frac{n+m}{2}} \leq R \cdot 2^{\frac{n-m}{2}}$, i.e. when $M \leq R$, then $T \approx R \cdot 2^{\frac{n-m}{2}}$, thus

$$T^2 M = R^2 \cdot 2^{(n-m)+m} = R^2 \cdot 2^n$$

We end up with new tradeoff ($N = 2^n$):

$$T^2 M = R^2 N,$$

where $M \leq R$.

New Algorithm: Comparison to Standard Algorithm

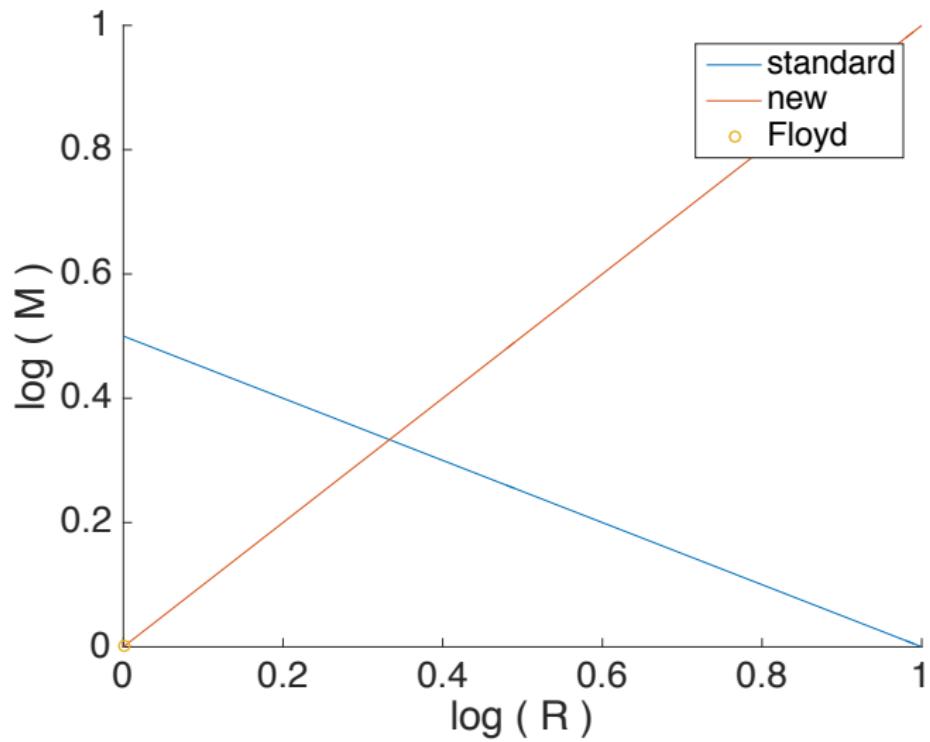
New $T^2M = R^2N$ against the standard $TM = N$

- ▶ **Better time** when $M < \frac{N}{R^2}$ (and $M \leq R$)
- ▶ **Better memory** when $T > R^2$ (and $T > \sqrt{RN}$)

If standard algorithm uses minimal time complexity $T < N^{\frac{2}{3}}$, then with new algorithm memory can be reduced from $\frac{N}{T}$ (which is $\geq N^{\frac{1}{3}}$) to $\frac{T^2}{N}$ (which is $< N^{\frac{1}{3}}$).

New Algorithm: The Missing Link

Smaller the ratio R , less memory is required by the new algorithm.



General

New Algorithm

Conclusion

Conclusions

- ▶ Consider using the new algorithm when dealing with unbalanced MITM problems
- ▶ Rule of thumb: if $R \leq 2^{\frac{n}{3}}$ then most likely the memory complexity of your attack can be reduced with the new algorithm (without increasing the time)
- ▶ There are numerous applications of the new algorithm: check our paper on eprint